

Now consider the transformation of $\phi(x)$

From which we derive $u(A) \alpha(u) u^{-1}(A) = a(Au)$

$$= \underbrace{\int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \{ u(A) \alpha(A-u) u^{-1}(A) e^{-i k \cdot (Ax)} + u(A) \alpha(A-u) u^{-1}(A) e^{i k \cdot (Ax)} \}}_{(2\pi)^3 2\pi} \\ (x \cdot u) \cdot u^{-1} = \underbrace{\int_{\mathbb{R}^3} \int_{\mathbb{R}^3} (-1)^{u \cdot u^{-1}}}_{V^p} x = x - u$$

Note $u \cdot x = u \times \text{grad } u$. Set $u = A^{-1} u'$

$$\left. \begin{aligned} &+ u(A) \alpha(u) u^{-1}(A) e^{-i k \cdot x} \\ &\times - u' \end{aligned} \right\} = \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \{ u(A) \alpha(A-u) u^{-1}(A) e^{-i k \cdot (Ax)} + u(A) \alpha(A-u) u^{-1}(A) e^{i k \cdot (Ax)} \}$$

$$u(A) \phi(x) u^{-1}(A) = \phi(Ax) = \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \{ a(Au) e^{-i k \cdot (Ax)} + a(Au) e^{i k \cdot (Ax)} \}$$

expressions

Recall the derivative of ϕ . This we can write the two

$$u(A) \alpha(u) u^{-1} = a(Au)$$

system, the field does not change. From this we derived

\Rightarrow only the space-time is rotated to the new coordinate

our scalar field to be $u(A) \phi(x) u^{-1} = \phi(Ax)$

We previously found the Lorentz transformation of

The Lorentz group

However, note the following:
 ① If $B_{\mu\nu}$ is symmetric on the left for μ, ν , so is
 the result on the right.

$$U_{\mu}(A) B_{\mu\nu}(x) U_{\nu}(A) = A_{\mu}^{\rho} A_{\nu}^{\sigma} B_{\mu\nu}(A)$$

We can define a tensor field also.

exactly as the index suggests.

Field: $U_{\mu}(A) A_{\nu}^{\rho}(x) U_{\rho}(A) = A_{\mu}^{\rho} A_{\nu}^{\sigma}(A)$. Transforms
 This is the template for transformation law of a vector

$$x^{\mu} = (\tilde{V})^{\mu}_{\nu} x^{\nu}$$

$$U_{\mu}(A) \tilde{V}^{\rho}_{\nu}(x) U_{\rho}(A) = V^{\rho}_{\mu} \tilde{V}^{\nu}_{\rho}(x)$$

$$U_{\mu}(A) \tilde{V}^{\rho}_{\nu}(x) U_{\rho}(A) = V^{\rho}_{\mu} \tilde{V}^{\nu}_{\rho}(x) \quad \text{or} \quad (\text{redefine } x \rightarrow A x)$$

and $U_{\mu}(A)$ on left, $U_{\rho}(A)$ on right

To bring this to a more standard form multiply by A^{μ}

$$\frac{x^{\mu}}{A^{\mu}} = \frac{\tilde{V}^{\rho}_{\nu}}{A^{\rho}} = \frac{V^{\rho}_{\mu}}{A^{\mu}} \quad \text{with } x^{\mu} = V^{\mu}_{\nu} x^{\nu} \quad (\tilde{V}^{\rho}_{\nu}(x)) = (V^{\rho}_{\mu}(A))$$

$$-U_{\mu}(A) \tilde{V}^{\rho}_{\nu}(x) U_{\rho}(A) e^{-ik \cdot x}$$

$$= - \int d^3k \sum_{\rho} (V^{\rho}_{\mu}(A)) \{ U_{\mu}(A) \tilde{V}^{\rho}_{\nu}(x) U_{\nu}(A) e^{-ik \cdot x}$$

$$\Leftrightarrow \text{Set } u_{\mu} = (V^{\rho}_{\mu}(A))$$

$$-U_{\mu}(A) \tilde{V}^{\rho}_{\nu}(x) U_{\nu}(A) e^{-ik \cdot x}$$

$$\text{we can write } U_{\mu}(A) \tilde{V}^{\rho}_{\nu}(x) U_{\nu}(A) = -i \int d^3k \sum_{\rho} \{ U_{\mu}(A) \tilde{V}^{\rho}_{\nu}(x) U_{\nu}(A) e^{-ik \cdot x}$$

$$U^{-1}(A) M_{\mu\nu} U(A) = \Lambda_\mu^\nu \Lambda_\nu^\lambda - M_{\mu\nu}$$

We can derive it + should be obvious, that

+ to determine their Lie algebra.

$$M_{\mu\nu} = -M^{\nu\mu} \text{ are the 6 generators of the Lie Lie. We want}$$

$$\text{in infinitesimal L.T. becomes: } U(1+\frac{i}{\hbar} w^{\mu\nu}) = I + \frac{i}{\hbar} w^{\mu\nu} M_{\mu\nu}$$

The unitary operator acting on quantum fields for

L.T. characterized by 6 parameters; 3 boost, 3 rotations

$$= g_{\mu\nu} + w^{\mu\nu} \delta_{\mu\nu} + w^{\mu\nu} f^{\rho}{}_{\rho} = g_{\mu\nu} + w^{\mu\nu}$$

$$\Leftrightarrow g_{\mu\nu} \{ j^{\mu}{}_{\alpha} + w^{\mu}{}_{\alpha} \} \{ j^{\nu}{}_{\beta} + w^{\nu}{}_{\beta} \} = g_{\mu\nu}$$

$$\text{Substitute into } g_{\mu\nu} \Lambda^{\mu}{}_{\alpha} \Lambda^{\nu}{}_{\beta} = g_{\mu\nu}$$

$$\text{begin by considering an infinitesimal L.T.: } A_{\mu\nu} = j^{\mu}{}_{\alpha} + w^{\mu}{}_{\alpha}$$

We must study the algebra associated with the L.G.

There are smaller ones than the vector rep. To find this,

irreducible reps. of the Lorentz group. It turns out that

representations. What we want to do now is find the

Lorentz group can be broken up into smaller, irreducible

point is that the tensor field representation of the

The quantity $g_{\mu\nu} B_{\mu\nu}(x)$ transforms as a scalar. The

$$\Rightarrow U^{-1}(A) g_{\mu\nu} B_{\mu\nu}(x) U(A) = \underbrace{g_{\mu\nu} \Lambda^{\mu}{}_{\alpha} \Lambda^{\nu}{}_{\beta}}_{g_{\mu\nu}} B_{\mu\nu}(A^{-1}x)$$

③ Multiply both sides by $g_{\mu\nu}$

② same if $B_{\mu\nu}$ is anti-symmetric

$\{g_{\mu\nu} W_{\alpha\beta} - g_{\alpha\beta} W_{\mu\nu}\}$
 $\{g_{\mu\nu} W_{\alpha\beta} + g_{\alpha\beta} W_{\mu\nu}\} = \frac{1}{2} \epsilon^{\mu\nu\alpha\beta} [g_{\mu\nu} W_{\alpha\beta} - g_{\alpha\beta} W_{\mu\nu}]$ \Rightarrow $\frac{1}{2} \epsilon^{\mu\nu\alpha\beta} [g_{\mu\nu} W_{\alpha\beta} - g_{\alpha\beta} W_{\mu\nu}]$
 Multiply both sides of the commutation relation by

operators by defining $J_i = \frac{1}{2} \epsilon^{\mu\nu\alpha\beta} W_{\mu\nu}^i$, $N = W^{00}$
 We can write these in terms of the rotational boost

$\{g_{\mu\nu} W_{\alpha\beta} - g_{\alpha\beta} W_{\mu\nu}\}$
 $\{g_{\mu\nu} W_{\alpha\beta} + g_{\alpha\beta} W_{\mu\nu}\} = ?$ we derive $[W_{\mu\nu}, W_{\alpha\beta}] = ?$

$$\begin{aligned}
 & \{g_{\mu\nu} W_{\alpha\beta} - g_{\alpha\beta} W_{\mu\nu}, g_{\mu\nu} W_{\gamma\delta} + g_{\nu\delta} W_{\mu\gamma}\} = \\
 & \quad \{g_{\mu\nu} W_{\alpha\beta} - g_{\alpha\beta} W_{\mu\nu}, g_{\mu\nu} W_{\gamma\delta} + g_{\nu\delta} W_{\mu\gamma}\} = \\
 & \quad g_{\mu\nu} W_{\alpha\beta} g_{\mu\nu} W_{\gamma\delta} - g_{\alpha\beta} W_{\mu\nu} g_{\mu\nu} W_{\gamma\delta} = \\
 & \quad g_{\mu\nu} W_{\alpha\beta} g_{\mu\nu} W_{\gamma\delta} + g_{\nu\delta} W_{\mu\gamma} g_{\mu\nu} W_{\alpha\beta} = \\
 & \quad [g_{\mu\nu} W_{\alpha\beta} + g_{\nu\delta} W_{\mu\gamma}] = [g_{\mu\nu} W_{\alpha\beta} + g_{\nu\delta} W_{\mu\gamma}] \left[W_{\mu\nu} \right]^{\frac{1}{2}} \left[W_{\alpha\beta} \right]^{\frac{1}{2}} \left[W_{\gamma\delta} \right]^{\frac{1}{2}}
 \end{aligned}$$

$$\begin{aligned}
 & g_{\mu\nu} W_{\alpha\beta} + g_{\nu\delta} W_{\mu\gamma} = \\
 & \quad g_{\mu\nu} W_{\alpha\beta} + g_{\nu\delta} W_{\mu\gamma} + g_{\mu\nu} W_{\alpha\beta} - g_{\nu\delta} W_{\mu\gamma} = \\
 & \quad \{g_{\mu\nu} W_{\alpha\beta} + g_{\nu\delta} W_{\mu\gamma}\} = \\
 & \quad \{g_{\mu\nu} W_{\alpha\beta} + 1\} g_{\mu\nu} W_{\alpha\beta} = 1
 \end{aligned}$$

parameter $w_{\mu\nu}$:

Expand out all quantities to linear order in the small

The algebra is just $SU(2) \otimes SU(2)$. We know exactly by representation theory from QM. Each $SU(2)$ is labeled by $\frac{1}{2}$ -integer values, called j or j' . Number of components are $2j+1$. Label reps as (j, j') .

Lowest reps: $(0,0)$ $(1,0)$ $(0,1)$ $(\frac{1}{2},0)$ $(0,\frac{1}{2})$ $(\frac{1}{2},\frac{1}{2})$ $(1,1)$ $(2,0)$

$$O = 0$$

$$[N_i^+, N_j^+] = \frac{1}{4} [J_i - iN_i, J_j + iN_j] = \frac{i}{4} \epsilon_{ijk} \{J_k - J_k' - iN_k + iN_k'\}$$

$$[N_i^+, N_j^+] = i \epsilon_{ijk} N_k^+$$

$$= i \epsilon_{ijk} N_k$$

$$[N_i^-, N_j^-] = \frac{1}{4} [J_i - iN_i, J_j - iN_j] = \frac{i}{4} \epsilon_{ijk} \{J_k + J_k' - iN_k + iN_k'\}$$

$$N_i^- = \frac{1}{2} \{J_i + iN_i\} \quad N_i^+ = \frac{1}{2} \{J_i - iN_i\}$$

$$\text{Define } N_i^{\pm} = \frac{1}{2} \{J_i \mp iN_i\} \Rightarrow J_i^{\pm} = N_i^{\pm} N_i^{\mp}$$

We can recognize the $SU(2)$ Lie algebra of angular momentum. J_i^{\pm} turns out we can make this even simpler

$$[J_a, J_b] = i \epsilon_{abc} J_c$$

\Rightarrow can find these similarly

$$[K_a, K_b] = -i \epsilon_{abc} J_c$$

$$[J_a, J_b] = i M_{ab} = i \epsilon_{abc} \partial_c$$

use of the identity $\epsilon_{ijk} \epsilon_{lmn} = \delta_{im} \delta_{jl} - \delta_{il} \delta_{jm}$ gives

Note that $(0, \frac{1}{2})$ and $(\frac{1}{2}, 0)$ are related by conjugation

Maxwell field strength tensor is $(1, 0) \oplus (0, 1)$

anti-symmetric, self-dual tensor $F_{\mu\nu} = \frac{1}{2} \epsilon_{\mu\nu\rho\sigma}$

$(1, 0) \oplus (0, 1) \Rightarrow 3$ -components each. Can be represented as a

$(\frac{1}{2}, \frac{1}{2}) \Rightarrow$ has spin- $\frac{1}{2}$ spin- $\frac{1}{2}$. Those are the vector fields. Time component is $\vec{\text{fields}}$. Space component is $\vec{\text{fields}}$. Spin- $\frac{1}{2}$, spatial is spin- $\frac{1}{2}$ to total

$(\frac{1}{2}, 0) \oplus (0, \frac{1}{2}) \Rightarrow$ spin- $\frac{1}{2}$, spin- $\frac{1}{2}$ fields

$(0, 0) \Rightarrow$ scalar

What are the possible ~~measures~~ of each rep? Note $T^a_i = N^i + N^+_i \Rightarrow$ just addition of $\frac{1}{2}$'s in QM

$$\left| \begin{array}{ccc} s_{11} & s_{12} & s_{13} \\ s_{21} & s_{22} & s_{23} \\ s_{31} & s_{32} & s_{33} \end{array} \right| = s_{11} s_{22} s_{33} - s_{11} s_{23} s_{32} - s_{12} s_{21} s_{33} + s_{12} s_{23} s_{31} + s_{13} s_{21} s_{32} - s_{13} s_{22} s_{31}$$

$$= \left\{ \frac{e}{\sqrt{S_{11}}} s_{11}^3 - \frac{e}{\sqrt{S_{11}}} s_{11}^3 e^{i\omega t} \right\} ?$$

$$s_{11}^3 = ? \quad \text{Replace } s_{11}^3 = \frac{e}{\sqrt{S_{11}}} - e^{i\omega t} ?$$

$\underbrace{\frac{e}{\sqrt{S_{11}}}}$

$$\left[\frac{e}{\sqrt{S_{11}}} \right] s_{11}^3 = e^{i\omega t} \left[\frac{e}{\sqrt{S_{11}}} \right]$$

We will show that $S_{11}^3 = \frac{e}{\sqrt{S_{11}}} e^{i\omega t}$

Consider the spatial parts of this:

$$\left\{ g_{uv} S_{11}^3 + g_{vu} S_{11}^3 \right\}$$

$$\text{Lorentz algebra: } [S_{uv}, S_{vu}] = i g_{uv} S_{uv} - i g_{vu} S_{vu}$$

The S_{11} must be $\pm 3x3$ matrices that satisfy the

$$L_a^b = \delta_a^b + i \epsilon_{abc} (S_{ab})^c$$

where $a=1,2$. For an infinitesimal transformation,

$$U(A)^\dagger T_a(x) U(A) = L_a^b(A) T_b(x)$$

They transform under L.T. as

Consider first the (V_A) or left-handed spinor fields

$$u(A_i^{-1} \Phi_i^*(x)) u_i = R_i^*(A_i \Phi_i^*(x))$$

To get the representation of a multiplies F_C ($C_{1/2}$). Note that we can write

$$(\Phi_i(x) J_+ - \Phi_i^*(x)) \Rightarrow \text{distribute this rep by a dot over } i\text{'s indices}$$

Now go to the $(C_{1/2})$ rep. We can get this one by summing $N_u \rightarrow M_u^+$ or equivalently by combining conjugate fields

$$\text{Set } w_{ij} = C_{ij} \theta_a, \quad w_{i0} = B_i \Leftarrow 1 + \frac{\partial}{\partial \theta_a} - \frac{\partial}{\partial \theta_a}$$

$$\text{becomes } L + \frac{\partial}{\partial \theta_a} w_{ij} C_{ij} \theta_a + \frac{\partial}{\partial \theta_a} w_{i0} C_{i0}$$

An in Finslerian L.T. acting as a spinor field

$$\Rightarrow S_{u0} = K_u \text{ as before, and } S_{u0} = \frac{\partial}{\partial \theta_a} K_u$$

$$\text{and } N_u^+ = 0 \text{ for this rep. Therefore, } K_u = \underline{K}_u$$

$$K_u = i(N_u - N_u^+)$$

$$\text{For } (\mathcal{A}, \mathcal{U}) \text{ fields. Recall that } J_u = N_u + N_u^+$$

group, S_{ij} gives us the angular momentum generators

$$\text{matrices. Recall } J_i = \frac{1}{2} \epsilon_{ijk} M_{jk} \text{ for the Lorentz}$$

\Rightarrow These furnish a representation in terms of θ_a

$$= i \bar{J}_{ik} S_{je}^l - i \bar{J}_{ie} S_{jk}^l + i \bar{J}_{je} S_{ik}^l - i \bar{J}_{ik} S_{ej}^l$$

$$\Rightarrow (S_{uv})_a^c x_{cd} = - (S_{uv})_d^b x_{ad}$$

$$\{ \mathcal{L}_a^c + \frac{i}{2} \omega_{uv} (S_{uv})_a^c \} \{ \mathcal{L}_b^d + \frac{i}{2} \omega_{uv} (S_{uv})_b^d \} x_{cd} = x_{ab}$$

causalities implies

Perform an infinitesimal LT on x_j to see what this

indicates. Specifically, we want $\mathcal{L}_a^c \mathcal{L}_b^d x_{cd} = x_{ab}$.
 If the L.G. were want same thing similar to spinor
 we get a Lorentz scalar. $g_{\mu\nu}$ is an invariant symbol.
 This told us that if contracted indices completely

easy because of the relation $A_\mu A_\nu g^{\mu\nu} = g_{\mu\nu}$
 simplest way possible. With vector indices, this was
 to describe their dynamics. We want to do this in the
 fields, we want to start building L.I. lagrangians
 now that we have the L.T. properties for both spinors

$$\Rightarrow (S_{uv})_i^j = - (S_{uv})_j^i$$

$$= \mathcal{L}_a^i = \mathcal{L}_a^i + \frac{i}{2} \omega_{uv} (S_{uv})_a^i$$

$$\text{Equate } (\mathcal{L}_a^i)_x = \mathcal{L}_a^i - \frac{i}{2} \omega_{uv} (S_{uv})_a^i$$

$$\text{law to obtain } U(A)^\dagger \gamma^a (x) U(A) = (U(A)^\dagger \gamma^a U(A))$$

We can also complex conjugate the $(\frac{1}{2} i)$ transformation.

Note $\mathcal{E}_{ab}^{bc} = \delta_a^c$, $\mathcal{H}_a(x) = \mathcal{H}(x)$ use $i + k$
 This is our first invariant symbol for spinor indices
 raised/lower spinor indices

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \mathcal{E}_{12}^3 -$$

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathcal{E}_{12}^3 : \overline{\overline{3}} = n$$

$$\begin{pmatrix} ? & 0 \\ 0 & ? \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \mathcal{E}_{12}^3 -$$

$$\begin{pmatrix} ? & 0 \\ 0 & ? \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \mathcal{E}_{12}^3 : \overline{\overline{2}} = n$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathcal{E}_{12}^3 -$$

$$n=1: \mathcal{E}_{12}^3 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \text{while}$$

Check for $n=1, 2, 3$

What matrix satisfies this property? $I + \Gamma$ turns out to be simple to find one: $X_{ab} = (\Gamma_a)^b = \mathcal{E}_{ab}$

$$\Rightarrow (\Gamma_a)^c x_b = -(\Gamma_b)^c x_a \Leftrightarrow \Gamma_a x_b - x_a \Gamma_b$$

$$\text{Specialize to } (S_{\mu\nu})^a_c = \frac{1}{2} \epsilon_{\mu\nu}^{ab} \Gamma_b^c$$

We will need to calculate more invariant symbols, in order to take derivatives of spinor fields.

There is obviously a similar symbol for the (∂_a) term.
as advertised, gives us a Lorentz scalar.

$$\text{Under L.T. } \partial_a X^a \rightarrow e^{ab} L^a_b \partial_a X^a = e^{ab} \partial_a X^a$$

$$\text{Consider } \partial_a X^a = \delta^{ab} \partial_b X^a = -\delta_{ba} X^a \partial_b X^a$$

What do we expect to get? If $\psi^+ \bar{\psi} = \text{a quantity}$ turns forms as a 4-vector we would expect to find

$$\text{Set } D = \frac{1}{2} (\partial_i - \partial_j) \cdot \vec{E} = \frac{1}{2} \partial_i (E_i - E_j)$$

We can simplify this. Note that it vanishes for $D=0$.

$$= \frac{1}{2} (E_i - E_j) \partial_i \vec{E}_j$$

The transformation becomes $\frac{1}{2} \vec{E} \cdot \{G_{ij}\}_{ab} - (G_{ia})_{ab} - (G_{jb})_{ab}$

$$S_{uv} \in S_{ij} = \frac{1}{2} \vec{E} \cdot G$$

$$w_{uv} \leftarrow w_{ij} = E_{ij} \vec{E}$$

Specialize to spatial transformations, for simplicity

$$\text{The RHS of above is } \frac{1}{2} w_{uv} (S_{uv})_{ab} - \delta_{ab} + \frac{1}{2} w_{uv} (G_{ab})_{ab}$$

Consider infinitesimal transformations; the linear term of

$$u(\alpha)^\dagger [\psi^+ \bar{\psi}] u(\alpha) = \psi^+ R^\dagger \bar{\psi} + \text{a la L a la}$$

Under L.T.

us to add a δu to form an invariant kinetic term.

We will show that this forms as a 4-vector, allowing

$$\psi^+ \bar{\psi} = u^\dagger u$$

Kinetic term for Fermionic fields consider the quantity

The other symbol we need is required to write a good

$X^+ \equiv X^a \eta^a$, $X^+ \eta^a \equiv X^a \eta^a$

To remove the plethora of spinor indices, we will define

Let's introduce a few notational issues before continuing

(ψ_1, ψ_2) and $(\bar{\psi}_1, \bar{\psi}_2)$ indices in the opposite order

There is a similar symbol $\tilde{\psi}^{ab} = (\bar{\psi}_1, \bar{\psi}_2)$ that ties together them

$$\begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \rightarrow \begin{pmatrix} \psi_1 & 0 \\ 0 & \psi_2 \end{pmatrix} + \begin{pmatrix} 0 & \psi_2 \\ \psi_1 & 0 \end{pmatrix} \leftarrow \begin{pmatrix} \bar{\psi}_1 & \bar{\psi}_2 \\ \bar{\psi}_2 & \bar{\psi}_1 \end{pmatrix}$$

Can write in matrix notation as

Note that we've found a better way

To make connection with the normal infinitesimal rotation

Same as above, proves that $\psi_+ \equiv \eta^a \psi_a$ transforms as

as a 4-vector.

$$= \frac{1}{2} \epsilon_{ijk} \epsilon^{kl} [g_{ij} - g_{ji}] \epsilon_{kl} = - \epsilon_{ijk} \epsilon^{kl} g_{ij} = \epsilon_{ijk} g_{ij}$$

Note that this vanishes for $\beta = 0$. Set $\beta = 0$

$$= \frac{1}{2} \epsilon_{ijk} \epsilon^{kl} [g_{ij} - g_{ji}] \epsilon_{kl}$$

$$= \frac{1}{2} \epsilon_{ijk} \epsilon^{kl} [g_{ik} - g_{ki}] \epsilon_{jl} + [g_{il} - g_{li}] \epsilon_{jk}$$

$$\Rightarrow \frac{1}{2} \sum_{i,j,k} (S_{ij}) \frac{\partial}{\partial \beta} \Rightarrow \text{note } S_{ij} = \frac{1}{2} [g_{ik} \eta_{jk} - g_{jk} \eta_{ik}]$$

Study this for a in infinitesimal transformations

Total derivative of motion

does not change eqs.

$$= i \dot{y}^a - \frac{d}{da} y^a - i \partial_a [y^a]$$

$$\text{use } (\frac{d}{da})^* = \frac{d}{da} = -i \partial_a y^a - \frac{d}{da} y^a \Rightarrow \text{I.B.P}$$

$$[i \dot{y}^a - \frac{d}{da} \partial_a y^a]^+ = -i \partial_a y^a \quad \text{from } (\frac{d}{da})^+ \leftarrow \text{flip a \leftrightarrow b}$$

$[i \dot{y}^a - \frac{d}{da} y^a]^+$ is Lorentz invariant, is it real?

We're now ready to write down a Lagrangian for our component field, try

$$\frac{d}{da} a^a - b^b = \delta^{ab} \quad \text{Same form as usual}$$

$$\Rightarrow \frac{d}{da} a^a - \frac{d}{db} b^b = \# = (\frac{d}{da})^{\frac{1}{2}} (\frac{d}{db})^{\frac{1}{2}} + (\frac{d}{db})^{\frac{1}{2}} (\frac{d}{da})^{\frac{1}{2}} = \#$$

$\begin{matrix} 1 \\ 1 \\ 1 \\ 1 \end{matrix}$

$a = a = 1, b = b = 2$

Set $\frac{d}{da} a^a - b^b = \# \delta^{ab}$. To work out $\#$, set

It must be proportional to $\epsilon_{abc} \epsilon^{abd}$ (no other alternatives!)

One other thing we will eventually need is $\frac{d}{da} a^a - b^b$

$$\text{Also, } (X^a)^+ = (Y^a)^+ = X^a + Y^a = X^a$$

columns
fields

$$= -4c \epsilon_{abc} X^b = 4c \epsilon_{abc} \epsilon_{abd} X^b = 4a X^a = 4X$$

$$\text{This allows us to write } X^a = X^a Y^a = \epsilon_{abc} X^b \epsilon^{acd} Y^d$$

We need one more relation to clean this up.

$$-\epsilon_{\mu\nu}(\vec{u}\vec{u})^* \epsilon^{\mu\nu} \partial_\mu \vec{u}^* - m \vec{u}^* = 0$$

$$-(\vec{u}\vec{u})^* \partial_\mu \vec{u}^* - m \vec{u}^* = 0$$

Take hermitian conjugate of this:

$$\vec{u}^* \partial_\mu \vec{u}^* - m \vec{u}^* = 0$$

With indices written out explicitly we have

Note that we can always choose $m^* = m$; if $m = m^\dagger$,
Rescale $\psi \rightarrow e^{-i\omega t} \psi$ \Rightarrow phase cancels out

$$\Rightarrow \overline{\partial S} = 0 \Leftrightarrow \vec{u}^* \partial_\mu \vec{u}^* - m^* \vec{u}^* = 0$$

get the equation of motion by varying this w.r.t. ψ^*
This is our free fermionic Lagrangian. It's easiest to

$$\text{at most } \Rightarrow f = \psi^* \partial_\mu \psi - \frac{1}{2} m^* \psi^* \psi$$

be C_4 or less for renormalizability. Can have two fields
Must keep mass dimension of terms in the Lagrangian to

$$\text{Start with } S = \int d^4x \psi^* \partial_\mu \psi + C_4 = C_m \frac{3}{2}$$

$$O = \begin{pmatrix} q+i & h \\ h & m \end{pmatrix} \begin{pmatrix} m & -m \\ -m & \frac{i\omega_b}{m} \end{pmatrix}$$

Dotted

$$O = \boxed{\begin{pmatrix} q+i & h \\ h & m \end{pmatrix} \begin{pmatrix} m & -m \\ -m & \frac{i\omega_b}{m} \end{pmatrix}}$$

Gives us a system of two equations for q and h

$$= i\omega_b q + h - mh = 0$$

$$= i\omega_b q + h - mh = 0$$

$$\Rightarrow -i\omega_b q - mh = 0$$

Pauli matrices

Use this above, write $(\underline{u}_{ab})^* = \underline{u}_{ba}$ by hermiticity of

$$\Rightarrow O, C_{ba}C_{ba}^* = G_{ab}^* = G_{ab}$$

$$\Rightarrow O = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \overline{m}$$

$$\Rightarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \overline{m}$$

$$(0, 1)(0, 1)(0, 1) = 3, \quad 3 = \overline{1 = m}$$

Study 3rd \underline{u}_{ab} gives $\#$ $\underline{u}_{ab} = \underline{u}_{ba}$ in matrix multiplication

We can define a 4-d.o.f Dirac field as $\psi = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix}$

This is the Dirac equation for a Majorana Field

$$(i\gamma_\mu \partial^\mu - m) \psi = 0$$

Can write in 4-component notation

$$\text{Dirac } \psi_\mu = \begin{pmatrix} 0 \\ \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix}, \quad \psi = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix}$$

$\mathcal{L} = \dot{\phi}_+^2 - \frac{1}{2} m^2 \phi_+^2 - \frac{1}{2} m^2 \phi_-^2$

Upon integration by parts, can write as

$$\mathcal{L} = \dot{\phi}_+^2 + \dot{\phi}_-^2 + \frac{1}{2} m^2 \phi_+^2 + \frac{1}{2} m^2 \phi_-^2$$

$$= \dot{\phi}_+^2 + \left(\frac{\partial}{\partial x^a} \phi_+ \right) \left(\frac{\partial}{\partial x^a} \phi_+ \right) + \dot{\phi}_-^2 + \left(\frac{\partial}{\partial x^a} \phi_- \right) \left(\frac{\partial}{\partial x^a} \phi_- \right)$$

mass terms in the Lagrangian. Also study

$$\mathcal{L} = \dot{\phi}_+ \dot{\phi}_+ + \dot{\phi}_- \dot{\phi}_- = \dot{\phi}_+ \dot{\phi}_+ + \dot{\phi}_- \dot{\phi}_- \rightarrow \text{all terms } F_\mu^\nu \text{ in}$$

$$\text{Multiply } \mathcal{L} = (\dot{\phi}_+, \dot{\phi}_-) = (\dot{\phi}_a, \dot{\phi}_a)$$

$$= \left(\frac{\partial}{\partial x^a} \phi_+ \right) \left(\frac{\partial}{\partial x^a} \phi_+ \right) + \left(\frac{\partial}{\partial x^a} \phi_- \right) \left(\frac{\partial}{\partial x^a} \phi_- \right)$$

$$= (\dot{\phi}_a, \dot{\phi}_a)$$

Let's see how to write the Lagrangian in explicit component

We can combine these into a 4-component Dirac Field $\psi = (\psi_+, \psi_-)$

$$\mathcal{L} = \dot{\psi}_+^2 + \dot{\psi}_-^2 + \frac{1}{2} m^2 \psi_+^2 + \frac{1}{2} m^2 \psi_-^2$$

$$(3-\gamma_5) \frac{\psi_+}{\gamma_5} = \psi_+ \quad \psi_+ = \frac{1}{\sqrt{2}} (\psi_+ + i\psi_2)$$

$$(3+\gamma_5) \frac{\psi_-}{\gamma_5} = \psi_- \quad \psi_- = \frac{1}{\sqrt{2}} (\psi_- + i\psi_2)$$

Suppose we have two fields, so that $\gamma_5^2 = 1$. Transform the

$$\mathcal{L} = \dot{\psi}_+^2 + \dot{\psi}_-^2 + \frac{1}{2} m^2 \psi_+^2 + \frac{1}{2} m^2 \psi_-^2$$

Our Lagrangian for the Majorana field is

$$\psi(x) = \sum \int d^3p [b_S(p) u_S(p) e^{ipx} + b_S^\dagger(p) v_S(p) e^{-ipx}]$$

Each eq. is a system of equations for each component of ψ . Will have two solutions which will label by s , d . Mu~~de~~ expansion is

$$(i\phi + m)v(p) = 0$$

vanish separately. Derive $(i\phi - m)u(p) = 0$

Act on these with $(i\phi - m)$, must have a e^{ipx} modes

spins.

$$\psi(x) = u(p)e^{ipx} + v(p)e^{-ipx}, \text{ where } u, v \text{ are 4 components}$$

Solve this the wave eq., will have a Fourier expansion like
The scalar field (consider a particular mode

$$= (i\phi + m)u = 0$$

$$\text{Note } \phi = \frac{1}{2} u^\dagger u = \frac{1}{2} \partial^\mu u \partial_\mu u = \frac{1}{2} (\partial^\mu \phi)(\partial_\mu \phi) = 0$$

$$\Rightarrow (i\phi + m)(i\phi - m)u = 0 \Leftrightarrow (-\phi^2 - m^2)u = 0$$

To solve this, act on by the operator $(i\phi + m)$

$$0 = \cancel{m} - \cancel{i\phi} ? \Rightarrow$$

$0 = \cancel{m} - \cancel{i\omega_n}$ $\Rightarrow i\omega_n = \cancel{m}$

We can therefore use $\phi = (\pm \omega_n)u \cancel{m} - \cancel{i\omega_n}$ for our Dirac

$$\lim_{n \rightarrow \infty} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = |0\rangle - u$$

$$\lim_{n \rightarrow \infty} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = |0\rangle + u \leftarrow \begin{pmatrix} u_1 & u_2 \\ u_3 & u_4 \end{pmatrix} \frac{e}{i} = \begin{pmatrix} u_1 & u_2 & u_3 & u_4 \\ u_4 & u_1 & u_2 & u_3 \\ u_2 & u_4 & u_1 & u_3 \\ u_3 & u_2 & u_4 & u_1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} = S^z u = \frac{e}{i} u$$

$$\begin{pmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{pmatrix}$$

Consider the u -spiral solutions,

$$h_{\lambda} = e^{\lambda t}$$

$$v_{\lambda} = v$$

$$u_2 = u_4$$

$$u_1 = u_3$$

$$C = C \begin{pmatrix} h_{\lambda} \\ v_{\lambda} \\ v_{\lambda} \\ v_{\lambda} \end{pmatrix} \begin{pmatrix} u_1 & u_2 & u_3 & u_4 \\ u_4 & u_1 & u_2 & u_3 \\ u_2 & u_4 & u_1 & u_3 \\ u_3 & u_2 & u_4 & u_1 \end{pmatrix}$$

In the rest frame, $\lambda = m \omega \Rightarrow$ have

$$(S^z)^2 \frac{e}{i} f = [S^z, d^2] f =$$

$$(S^z)^2 \frac{e}{i} f = [f, d^2] = f (S^z)^2$$

\Rightarrow will later need to

$$S^z v^{\pm}(t) = \pm \frac{1}{2} v^{\pm}(t)$$

$$S^z u^{\pm}(t) = \mp \frac{1}{2} u^{\pm}(t)$$

should be the following eigenfunctions of the spin operator:

Dirac Field is $S^z = \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$, and we will demand our state can show that the angular momentum operator for the

We will solve these by going to the rest frame where $\vec{p} = 0$

To get the solution for arbitrary f , we now boost along the z -axis:

$$V^z(p) = e^{ip_z \int d\tau \{ \dot{\eta}^z \eta^z \} (\tau)}$$

$$U^z(p) = e^{ip_z \int d\tau \{ \dot{\eta}^z \eta^z \} (\tau)}$$

Similarly, we have $V^z(p) = V^z$,