

HW#9 Solutions

Problem 1 (P&S 9.1).

$$\mathcal{L} = -\frac{1}{4}(F_{\mu\nu})^2 + (\partial_\mu\phi)^*(\partial^\mu\phi) - m^2\phi^*\phi.$$

(a). We will go to the Euclidean space such that

$$\begin{aligned}\mathcal{L}_E &= \frac{1}{4}(F_{\mu\nu})^2 + (\partial_\mu\phi)^*(\partial^\mu\phi) + m^2\phi^*\phi. \quad (\text{Contracted w/ } S_{\mu\nu}!) \\ &= \mathcal{L}_E^{\text{free}} + \mathcal{L}_E^{\text{int.}}\end{aligned}$$

$$\mathcal{L}_E^{\text{free}} = \frac{1}{4}(F_{\mu\nu})^2 + \partial_\mu\phi^*\partial^\mu\phi + m^2\phi^*\phi$$

$$\mathcal{L}_E^{\text{int.}} = -ieA_\mu(\phi^*\partial_\mu\phi - \partial_\mu\phi^*) + e^2A^2\phi^*\phi.$$

The complex scalar propagator is determined by

$$\int D\phi^* D\phi e^{-S_E^{\text{free}}[\phi, \phi^*] - J^*\phi - J\phi^*}$$

This is an integral w/ a quadratic form in the exponent,

and can be performed using one of the identities

derived in class:

$$\int Dz^* dz e^{-(\frac{1}{2}Az^*)^2 - b^*z^* - z^*b} = \frac{e^{\frac{b^*b}{2A}}}{\det A}$$

A⁻¹ in this case is given by $\int \frac{d^4p}{(2\pi)^4} e^{ip\cdot x} \frac{1}{p_E^2 + m^2}$

which corresponds to the propagation

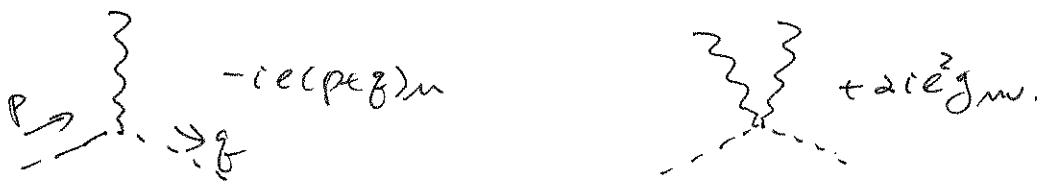
P12

$$\phi \rightarrow \phi^* \quad \frac{1}{p_E^2 + m^2} \quad \xrightarrow{\text{Going back to Minkowski}} \quad \frac{i}{p^2 - m^2 + i\epsilon}$$

The photon propagator, on the other hand, has been derived in textbook

$$A_\mu A_\nu = \frac{-i}{p^2 + i\epsilon} (\eta_{\mu\nu} + (\xi - 1) \frac{p_\mu p_\nu}{p^2})$$

The interaction vertices can be read off as in before.
(or see HW #10 in QFT I, Fall 2008!)



(b). There's only one diagram at the tree level for



Let's use the Feynman gauge $\xi = 1$:

$$iM = \left[\bar{u}(k') (i\gamma^\mu) u(k) \right] \times (-ie(p-p')^\mu) \times \frac{-i\delta_{\mu\nu}}{(k+k')^2} = \frac{e^2}{S} (p-p')^\mu \bar{u} \gamma^\mu u$$

$$\frac{1}{4} S |M|^2 = \frac{e^4}{S^2} \left[2(k \cdot p - k \cdot p') (k \cdot p - k' \cdot p') - (k \cdot k') (p \cdot p')^2 \right]$$

The kinematics are

$$S = (k \cdot k')^2 = 4E_{cm}^2$$

$$k \cdot p = k' \cdot p' = E^2 - |\vec{k}|(|\vec{p}| \cos \theta) \sim E^2(1 - \beta \cos \theta)$$

$$k' \cdot p = k \cdot p' \approx E^2(1 + \beta \cos \theta).$$

$$k \cdot k' \approx 2E^2$$

$$(p \cdot p')^2 = 4E_{cm}^2 \beta^2. \quad \beta = \frac{|\vec{p}|}{E} = \sqrt{1 - \frac{m_p^2}{E^2}}$$

$$\Rightarrow \frac{1}{4} \sum |m_i|^2 = \frac{1}{2} e^4 \beta^2 \sin^2 \theta$$

$$\frac{d\sigma}{dS_{cm}} = \frac{(\vec{p})}{|\vec{k}|} \frac{1}{64\pi^2 S^4} \sum |m_i|^2 = \frac{\alpha^2}{8S} \beta^3 \sin^2 \theta$$

$$\text{or } \sigma = \frac{\pi \alpha^2}{3S} \times \beta^3$$

as for $e^+e^- \rightarrow \mu^+\mu^-$ (P&S 5.10, 5.13)

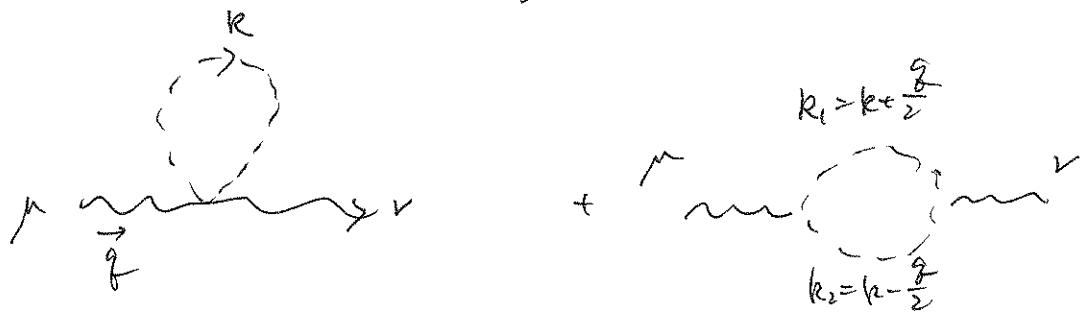
$$\frac{d\sigma}{dS_{cm}} = \frac{\alpha^2}{4E^2} \beta \left[\left(1 + \frac{m_\mu^2}{E^2} \right) + \beta^2 \cos^2 \theta \right]$$

$$\sigma_{tot} = \frac{4\pi \alpha^2}{3E_{cm}^2} \beta \cdot \left(1 + \frac{m_\mu^2}{E^2} \right).$$

So Scalars prefer $\theta = 90^\circ$ while for $\mu^+\mu^-$ (or $\bar{f}f$) they prefer $\theta = 0$. Also near threshold $E \approx 2m_f, 2m_\mu$, the Scalar cross-section grows much slower due to β^3 suppression!

(P.4)

(c) There are two diagrams



$$iM^{\mu\nu} = \int \frac{d^d k}{(2\pi)^d} (2ie^2 g_{\mu\nu}) \frac{i}{k^2 - m_\phi^2} + \int \frac{d^d k}{(2\pi)^d} [ie \cdot 2k_\mu] [ie \cdot 2k_\nu] \frac{i}{k^2 - m_\phi^2} \frac{i}{(k + \frac{q}{2})^2 - m_\phi^2}.$$

Following the hint from the textbook :

$$\int \frac{d^d k}{(2\pi)^d} (2ie^2 g_{\mu\nu}) \frac{i}{k^2 - m_\phi^2} = \int \frac{d^d k}{(2\pi)^d} \frac{(ie^2 g_{\mu\nu}) \left[i \left[(k - \frac{q}{2})^2 - m_\phi^2 \right] + i \left[(k + \frac{q}{2})^2 - m_\phi^2 \right] \right]}{\left[(k - \frac{q}{2})^2 - m_\phi^2 \right] \left[(k + \frac{q}{2})^2 - m_\phi^2 \right]}$$

$$\Rightarrow iM^{\mu\nu} = \int \frac{d^d k}{(2\pi)^d} \frac{-2e^2 g_{\mu\nu} \left[k^2 + \frac{1}{4}q^2 - m_\phi^2 \right] + 4e^2 k_\mu k_\nu}{\left[(k - \frac{q}{2})^2 - m_\phi^2 \right] \left[(k + \frac{q}{2})^2 - m_\phi^2 \right]}$$

$$\frac{1}{\left[(k - \frac{q}{2})^2 - m_\phi^2 \right] \left[(k + \frac{q}{2})^2 - m_\phi^2 \right]} = \int_0^1 dx \frac{1}{x^2 - \Delta + i\varepsilon}.$$

$$\text{Where } x = k + (k - \frac{1}{2})q, \quad \Delta = \frac{x(x-1)q^2 + m_\phi^2}{x(x-1)q^2 + m_\phi^2 + 2e^2 g_{\mu\nu} q^2 (k - \frac{1}{2})^2}.$$

$$\Rightarrow iM^{\mu\nu} = \int_0^1 \frac{d^d k}{(2\pi)^d} \frac{-4e^2 \left[g_{\mu\nu} q^2 - g_\mu g_\nu \right] (x - \frac{1}{2})^2 - 2e^2 g_{\mu\nu} \left[x^2 + \frac{1}{4}q^2 - m_\phi^2 \right] + 4e^2 \frac{d^2}{dx^2} g_{\mu\nu}}{\left[x^2 - \Delta + i\varepsilon \right]^2}.$$

The terms that are not gauge invariant evaluate to zero.

$$\text{and } iM^{\mu\nu} = i(g_{\mu\nu} q^2 - f^\mu f^\nu) \Pi(q^2)$$

P.5

$$i\bar{\Pi}(q^2) = -4e^2 \int_0^1 dx \int \frac{d^d k}{(2\pi)^d} \frac{(x-\frac{1}{2})^2}{[k^2 - \Delta]^2}$$

$$= -4e^2 \int_0^1 dx (x-\frac{1}{2})^2 \frac{i}{(4\pi)^d} \frac{\Gamma(d-\frac{d}{2})}{\Gamma(d)} \left(\frac{1}{\Delta}\right)^{2-\frac{d}{2}}$$

$$\approx -4i \int_0^1 dx (x-\frac{1}{2})^2$$

$i\bar{\Pi}(q^2) - i\bar{\Pi}(q^2=0)$ is finite and the observed on-shell quantity

$$i\bar{\Pi} \equiv i(\bar{\Pi}(q^2) - \bar{\Pi}(q^2=0)) = -\frac{i\alpha}{\pi} \int_0^1 dx (x-\frac{1}{2})^2 \log \left[\frac{m^2}{x(1-x) q^2 + m^2} \right]$$

In the limit $-q^2 \gg m^2$

$$i\bar{\Pi}(q^2) \propto \rightarrow -\frac{\alpha}{12\pi} \log \frac{m^2}{-q^2}$$

which is $\frac{1}{4}$ of eq.(7.91) in P&S

$$(\text{Feynman}) \quad \bar{\Pi}_2(q^2) = -\frac{2\alpha}{\pi} \int_0^1 dx x(1-x) \log \frac{m^2}{-x(1-x) q^2 + m^2}$$

$$\rightarrow -\frac{\alpha}{3\pi} \log \frac{m^2}{-q^2}$$

P.6.

Problem 2

$$Z[J] = \frac{1}{Z_0} \int e^{i \int dx V(-i \frac{\delta}{\delta J})} Z_{\text{free}}[J]$$

$$Z_{\text{free}}[J] = Z_0 e^{-\frac{1}{2} \int dx dy J(x) D_F(x-y) J(y)}$$

$$V(\phi) = \lambda \phi^4/4!$$

(a).

It's straightforward to compute the functional derivatives to get

$$\begin{aligned} G^{(2)}(x_1, x_2) &= D_F(x_1 - x_2) - \frac{\lambda}{2} \int dy D_F(x_1 - y) D_F(y - y) D_F(y - x_2) \\ &\quad + \frac{\lambda^2}{6} \int dx dy D_F(x_1 - x) D_F^3(x - y) D_F(y - x_2) \\ &\quad + \frac{\lambda^2}{4} \int dx dy D_F(x_1 - x) D_F^2(x - y) D_F(y - y) D_F(x - x_2) \\ &\quad + \frac{\lambda^2}{4} \int dx dy D_F(x_1 - x) D_F(x - x) D_F(x - y) D_F(y - y) D_F(y - x_2) \\ &\quad + O(\lambda^3) \end{aligned}$$

$$\begin{array}{c} \text{---} \textcircled{m} \text{---} = \longrightarrow + \overline{\textcircled{O}} + \overline{\textcircled{O}} \text{---} + \overline{\textcircled{S}} \\ \qquad \qquad \qquad + \underline{\textcircled{O} \textcircled{O}} \end{array}$$

(b)

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$$\begin{aligned}
 G^{(4)}(x_1, x_2, x_3, x_4) = & -\lambda \int d^4x D_F(x_1-x) D_F(x_2-x) D_F(x_3-x) D_F(x_4-x) \\
 & + \frac{\lambda^2}{2} \int d^4x d^4y \left\{ D_F^2(x-y) \left[D_F(x_1-x) D_F(x_2-x) D_F(x_3-x) D_F(x_4-y) \right. \right. \\
 & + \cancel{D_F(x_1-x) D_F(x_3-x) D_F(x_2-y) D_F(x_4-y)} \\
 & \left. \left. + D_F(x_1-x) D_F(x_4-x) D_F(x_2-y) D_F(x_3-y) \right] \right. \\
 & \left. + D_F(y-y) D_F(x-y) \left[D_F(x_1-x) D_F(x_2-x) D_F(x_3-x) D_F(x_4-y) \right. \right. \\
 & \left. \left. + \text{cyclic permutations} \right] \right\} + O(\lambda^3)
 \end{aligned}$$

$$\begin{aligned}
 \text{Diagram} &= X + \cancel{X} + \cancel{X} + \cancel{X} + X \\
 &+ \cancel{X} + \cancel{X} + \cancel{X}.
 \end{aligned}$$