

K Corrections for Dummies

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1 Motivation

- How do we combine SDSS results with other Hubble diagrams using different magnitude systems ?
- Develop software and verify K-corrections quoted in earlier papers.
- Global check of simulation + K-cor + fitter:
 $\Omega_{\Lambda, M} \rightarrow$ simulation \rightarrow observer magnitude \rightarrow
K-correction \rightarrow rest frame magnitude [B or g] \rightarrow
fitter $\rightarrow \Omega_{\Lambda, M}$

2 Magnitudes for Dummies

From Bessell et al., AAS, **333** 231 (1998),

$$m_\lambda(i) = -2.5 \log \left[\frac{\int f_\lambda(\lambda) S_i(\lambda) d\lambda}{\int S_i(\lambda) d\lambda} \right] - 21.100 - zp_\lambda \quad (1)$$

$$m_\nu(i) = -2.5 \log \left[\frac{\int f_\nu(\nu) S_i(\nu) d\nu}{\int S_i(\nu) d\nu} \right] - 48.598 - zp_\nu \quad (2)$$

A few comments:

- "21.100" = $-2.5 \log(3.63 \times 10^{-9})$
(defines **STMAG** at $\bar{\lambda}_V = 5450 \text{\AA}$ for Vega, $erg/s/cm^2/\text{\AA}$)
- $10^{(48.598-21.100)/2.5} = 10^{11} = d\nu/d\lambda = c/\bar{\lambda}_V^2$
(defines **ABmag**)
- rare to find magnitude definition
(only Bessell-98 and SDSS calib paper).
- "zp" obtained from Vega SED (which one ??)
- Note that λ and ν flux integrals are the same, but filter integrals are not!

$$\begin{aligned} \int f_\lambda(\lambda) S(\lambda) d\lambda &= \int f_\nu(\nu) S(\nu) d\nu \\ \int S(\lambda) d\lambda &\neq \int S(\nu) d\nu \end{aligned}$$

For SDSS magnitude :

- $d\nu \rightarrow d\nu/\nu$ and $48.598 \rightarrow 48.600$
(and no zero-points).
- note that

$$f_\nu \frac{1}{\nu} d\nu = \frac{dE}{d\nu} \frac{1}{\nu} d\nu = h \frac{dN_\gamma}{d\nu} d\nu = h N_\gamma \quad (3)$$

SDSS magnitude is a “count-flux” magnitude.

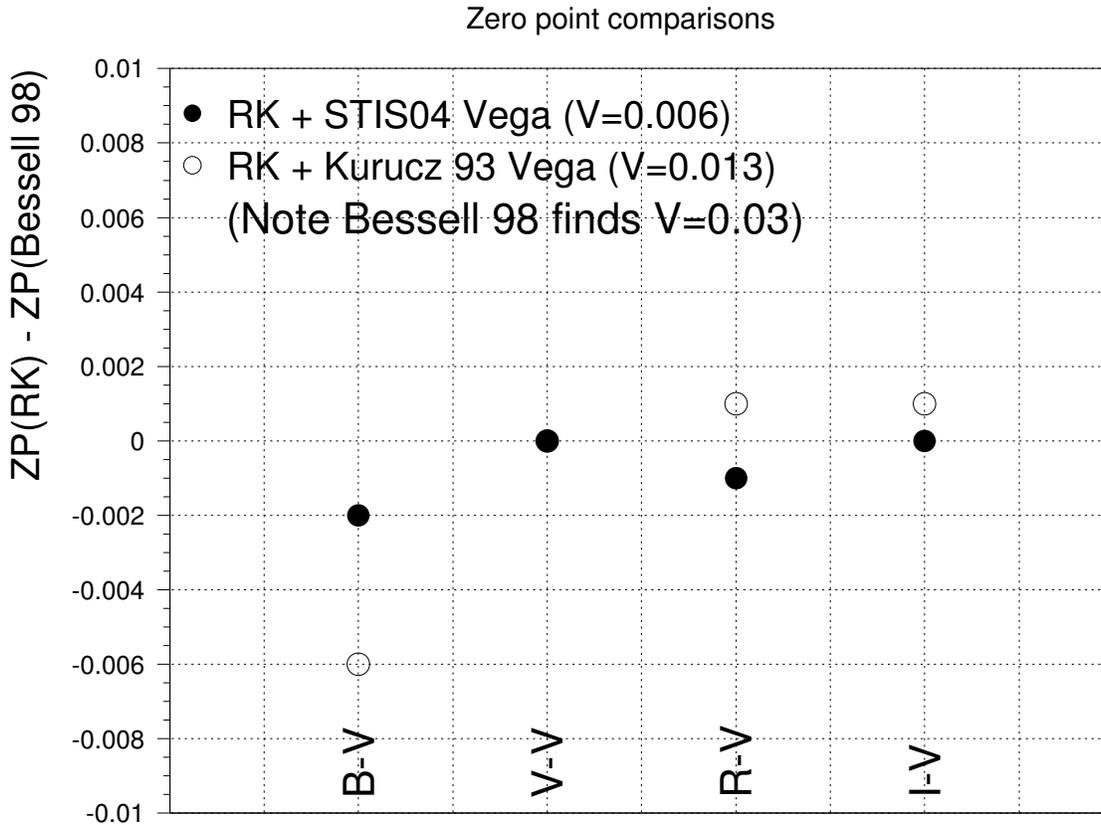


Figure 1: Zero point comparisons between RK and Bessell98. RK uses filter transmissions from Table 2 in Bessell90 [Bessell, PASP, **102** 1181 (1990)] and uses Vega models from STIS94 (`alpha_lyr_stis_002.fits`) and also from downloading model from Kurucz93. Bessell98 quotes Kurucz94 Vega model. $m_\lambda(V)$ differs by ~ 0.02 mags. Colors agree to < 0.002 mags, except for B-V when RK uses Kurucz93.

3 Definition of K Correction

K correction “ K_{ro} ” defined by

$$m_o = M_r + K_{ro} + \mu + A_r + A_o$$

where

- m_o = observed magnitude (in redshifted frame).
- M_r = absolute magnitude in rest frame.
- $\mu = -5\log[10pc/d_L(z)]$ depends on cosmological parameters Ω_Λ , Ω_m , w , etc ...
- A_r and A_o are extinctions for the SN-host (rest) and our galaxy (observer frame).

Below I ignore μ and $A_{r,o}$.

Discussion follows closely from
Nugent2002: astro-ph/0205351

3.1 Luminosity Distance

$$d_{L,\epsilon} = (1+z) \int dz' / H(z') \quad (4)$$

$$d_{L,\gamma} = \sqrt{1+z} \int dz' / H(z') \quad (5)$$

where ϵ, γ refer to “energy” and “photon”.

- Note that redshifting of energy causes difference:
 $[d_{L,\epsilon}/d_{L,\gamma}]^2 = 1+z$
- Standard literature: $d_{L,\epsilon} \rightarrow d_L$.
- in Hubble diagram,

$$m_B^{\text{eff}} = M_B + \mu$$

where $\mu = -5\log[10pc/d_L(z)]$, and $M_B \sim -18.5$

3.2 K Correction Formula

$$K_{ro}^\epsilon = 2.5 \log \left[(1+z) \times \frac{\int f_\lambda(\lambda) S_r(\lambda) d\lambda}{\int f_\lambda(\lambda/(1+z)) S_o(\lambda) d\lambda} \right] \quad (6)$$

$$- 2.5 \log \left[\frac{\int \mathcal{Z}_r^\epsilon(\lambda) S_r(\lambda) d\lambda}{\int \mathcal{Z}_o^\epsilon(\lambda) S_o(\lambda) d\lambda} \right]$$

$$K_{ro}^\gamma = \left[2.5 \log z \right] \times \frac{\int \lambda f_\lambda(\lambda) S_r(\lambda) d\lambda}{\int \lambda f_\lambda(\lambda/(1+z)) S_o(\lambda) d\lambda} \quad (7)$$

$$- 2.5 \log \left[\frac{\int \lambda \mathcal{Z}_r^\gamma(\lambda) S_r(\lambda) d\lambda}{\int \lambda \mathcal{Z}_o^\gamma(\lambda) S_o(\lambda) d\lambda} \right]$$

where

- $f_\lambda(\lambda) = dE/d\lambda$ (SED) for SN
- $\mathcal{Z}(\lambda) =$ SED of reference star with $m_\lambda = 0$ in all filters.
- $S_o(\lambda) =$ transmission of observer filter “o.”
- $S_r(\lambda) =$ transmission of rest-frame filter “r.”

Comments:

- Use Johnson filters as indicated in Nugent 2002.
- Could not find any discussion of $\mathcal{Z}(\lambda)$; I use Kurucz93 Vega SED with zero points applied (Eq. 1)
- $K_{ro}^{\epsilon, \gamma}$ are both defined to be used with $d_L = d_{L, \epsilon}$.
- $|K_{ro}^{\epsilon} - K_{ro}^{\gamma}|$ is typically < 0.01 mag.
- K_{ro}^{ϵ} valid for both m_{λ} and m_{ν} systems.
(note K_{ro}^{ϵ} definition has no $\int S(\lambda)d\lambda$ terms)
- In limit when $S_r = S_o = 1.000$ at all λ :

$$K_{ro}^{\epsilon} = 0.0$$
$$K_{ro}^{\gamma} = -2.5\log(1 + z)$$

- Beware: “ $\int \mathcal{Z}_r^{\gamma}(\lambda)S_r(\lambda)d\lambda$ ” is sometimes called a zero-point, but it is NOT a zero-point [because it’s not divided by $\int S(\lambda)d\lambda$]. Must do brute-force integration.

3.3 K Correction Formula for SDSS

- Since SDSS uses photon-count magnitude system, use $K_{ro}^\gamma (r, o = u, g, r, i, z)$.
- But we do not have SEDs for zero-mag stars.
- Therefore, re-write K correction as:

$$K_{ro}^\gamma = 2.5 \log \left[(1+z) \times \frac{\int f_\nu(\nu) S_r(\nu) \frac{1}{\nu} d\nu}{\int f_\nu(\nu(1+z)) S_o(\nu) \frac{1}{\nu} d\nu} \right] \quad (8)$$

$$- 2.5 \log \left[\frac{\int S_r(\nu) \frac{1}{\nu} d\nu}{\int S_o(\nu) \frac{1}{\nu} d\nu} \right]$$

- Raises analysis issue. To include SDSS data on other [high-z] Hubble diagrams, do we
 - convert observed SDSS mag to Johnson, then K-correct within Johnson system
** or ***
 - K-correct SDSS magnitudes, then convert rest frame SDSS magnitudes to Johnson system.

4 Comparisons with Nugent 2002

Results from RK code are compared with results from astro-ph/0205351.

- Values from figures extracted using ruler and eyeballs.
- SN templates from `supernova.lbl.gov/~nugent/spectra.html`
- SN templates include smooth fudge to match photometry, to correct for host galaxy reddenning, and to correct for color vs. stretch.
- RK code written in plain simple C.
(input file specifies filters, SN templates, Vega SED, etc ...)

Table 2 of Nugent, Kim, Perlmutter, 2002

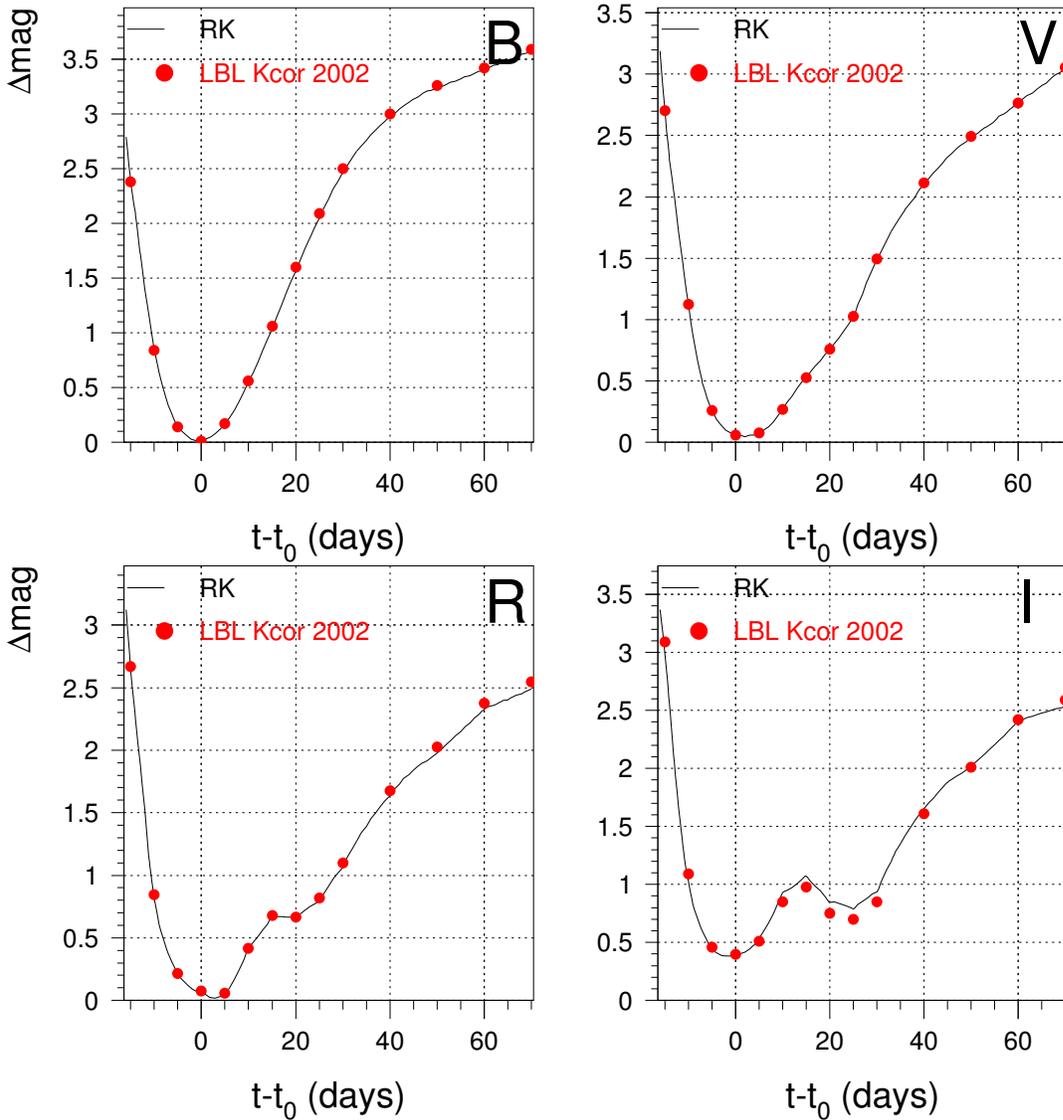


Figure 2: SN template magnitude vs. epoch for RK and from Nugent 2002 magnitude table. RK uses Johnson filters [as indicated in Nugent2002] and Bessell definition. Although shapes look good, offsets were needed in B,V,R,I-bands of 0.01, -0.005 , 0.007, -0.02 mag, respectively. We likely have different magnitude definitions ???

Table 2 of Nugent, Kim, Perlmutter, 2002

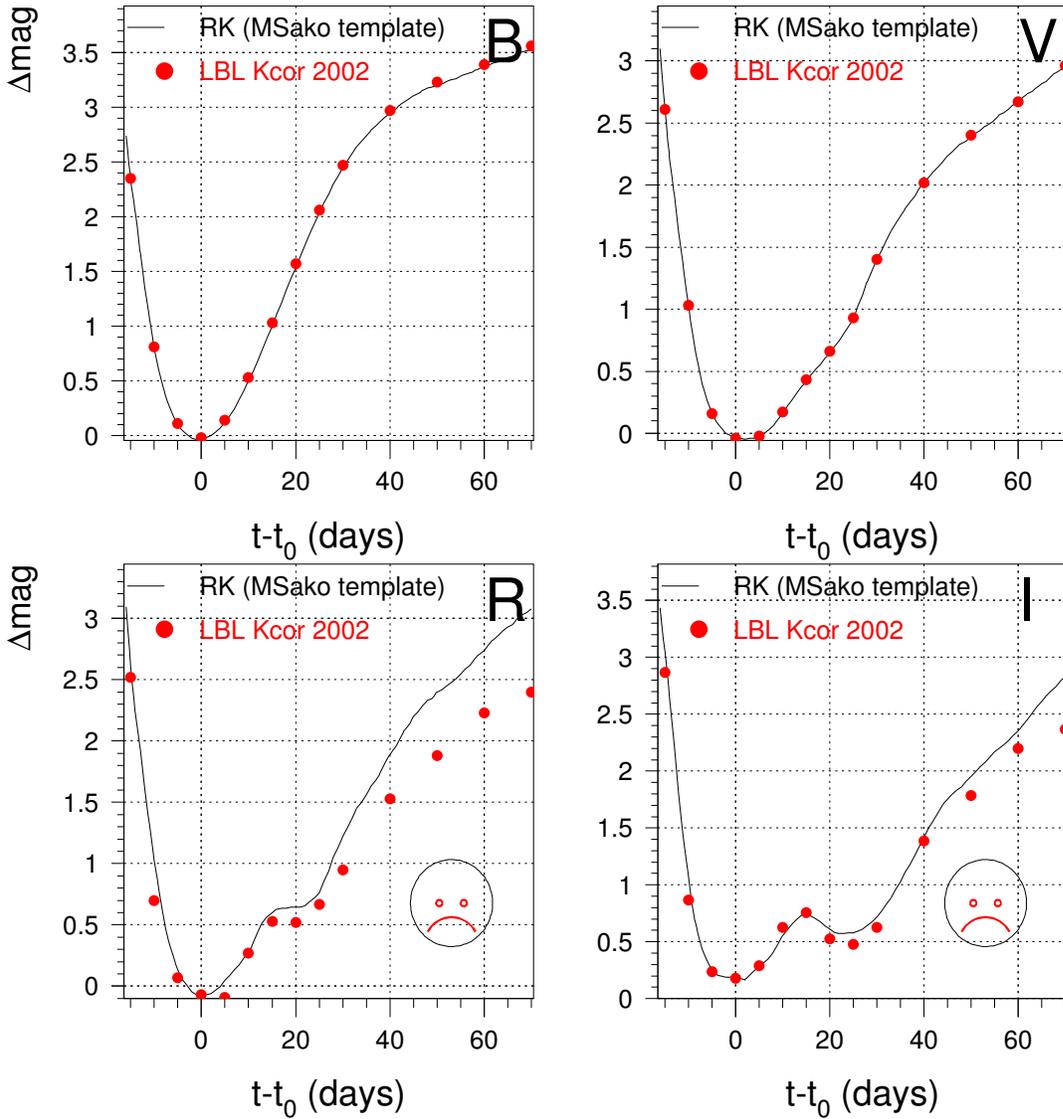


Figure 3: Same as previous plot, but RK curve uses SN templates from Sako (i.e., snap) that were used for SDSS/SN id in Fall 2004. There is some discrepancy at late epochs in R and I-bands. B,V,R,I offsets differ by -0.04 , -0.1 , -0.16 , -0.25 mag, respectively.

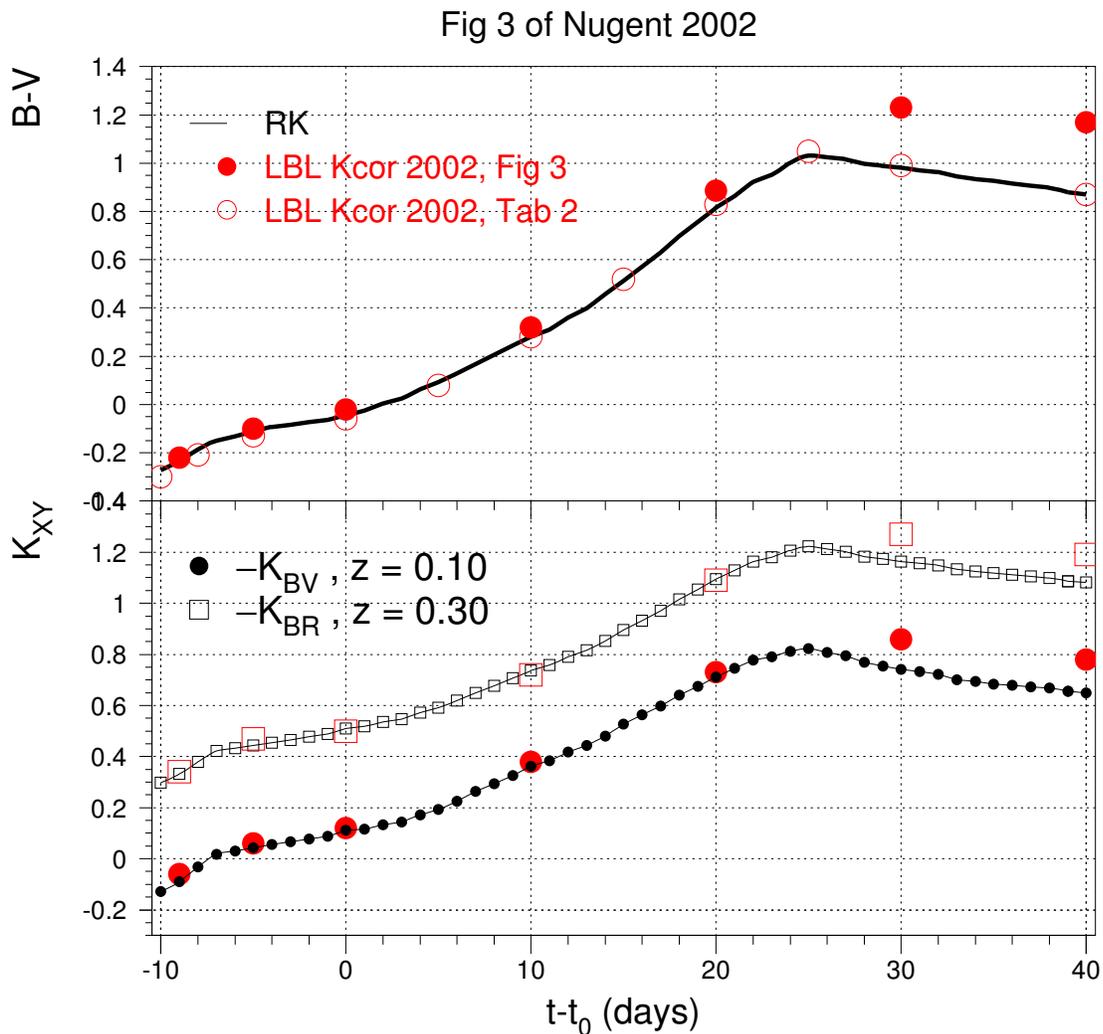


Figure 4: Top: $B-V$ vs. epoch in days, for SN Ia template. RK $B-V$ compares well with Table 2 of Nugent2002, but shows discrepancy in his Fig.3 beyond 25 days; this indicates internal discrepancy in Nugent 2002. Bottom: $-K_{BV}$ and $-K_{BR}$ vs. day for redshifts indicated on plot. Red squares and solid dots are read from Fig.3 in Nugent2002.

Fig 5 of Nugent 2002

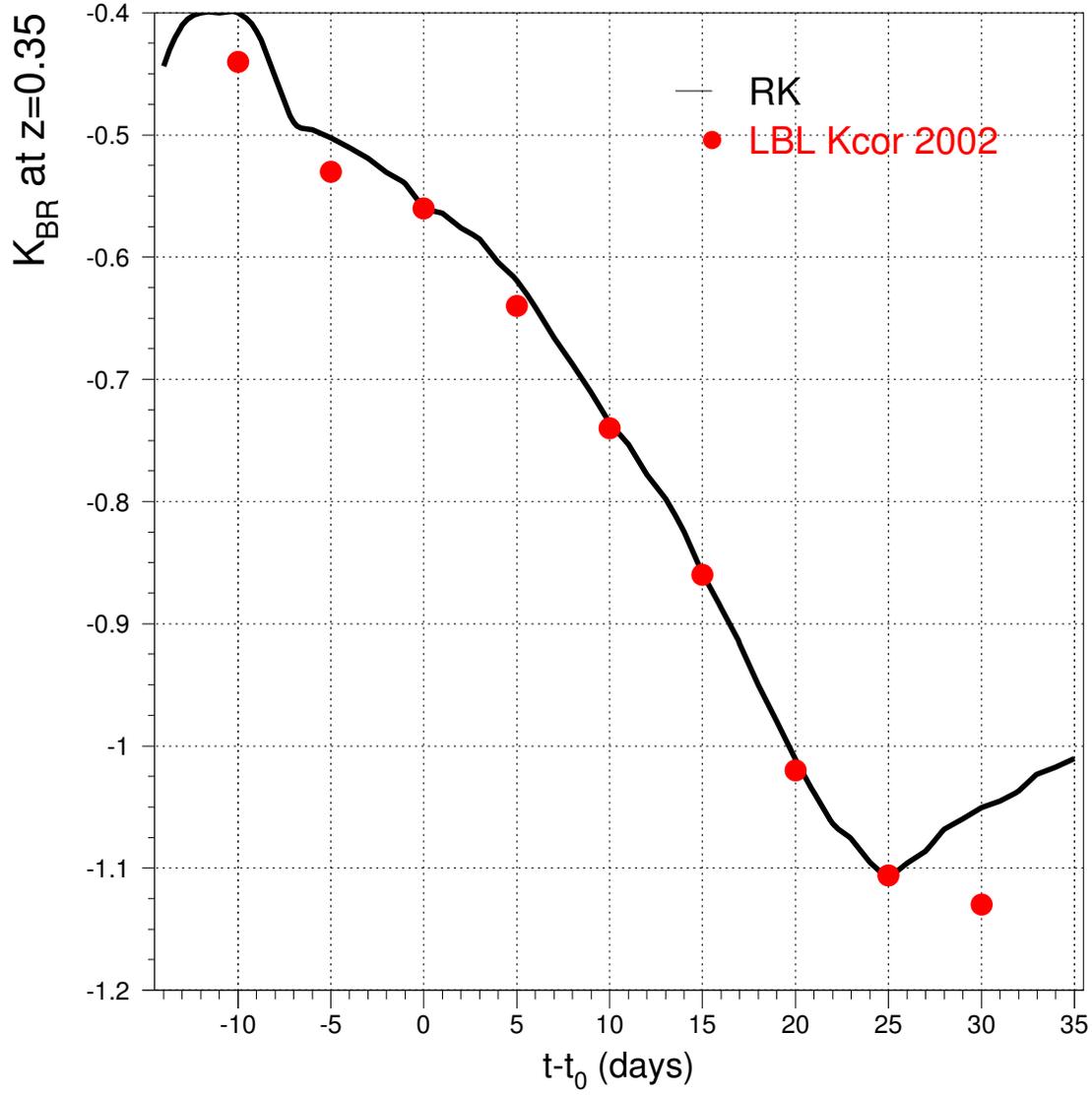


Figure 5: K_{BR} vs. day at $z = 0.35$.

5 Nugent-Riess SN Template Comparisons

- Nugent templates are from Nugent's public web-site, and they are described in a published technical article.
- Riess templates obtained through middle-man (John M.). Description based on John's memory.
- Comparison is probably unfair, but let's compare them anyway.

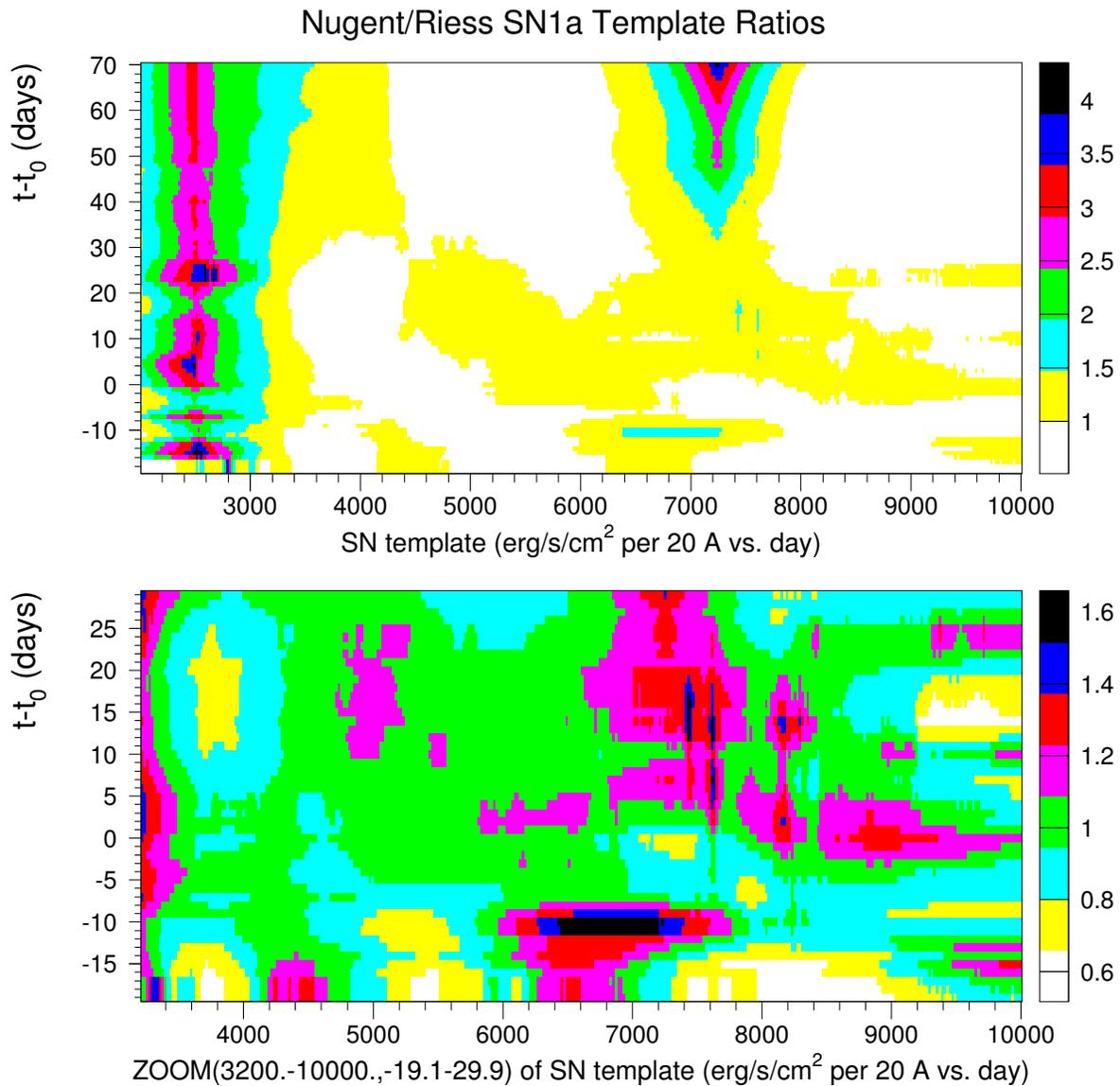


Figure 6: SN Ia flux ratio for Nugent/Riess templates. Flux ratio is shown in bins of wavelength and epoch.

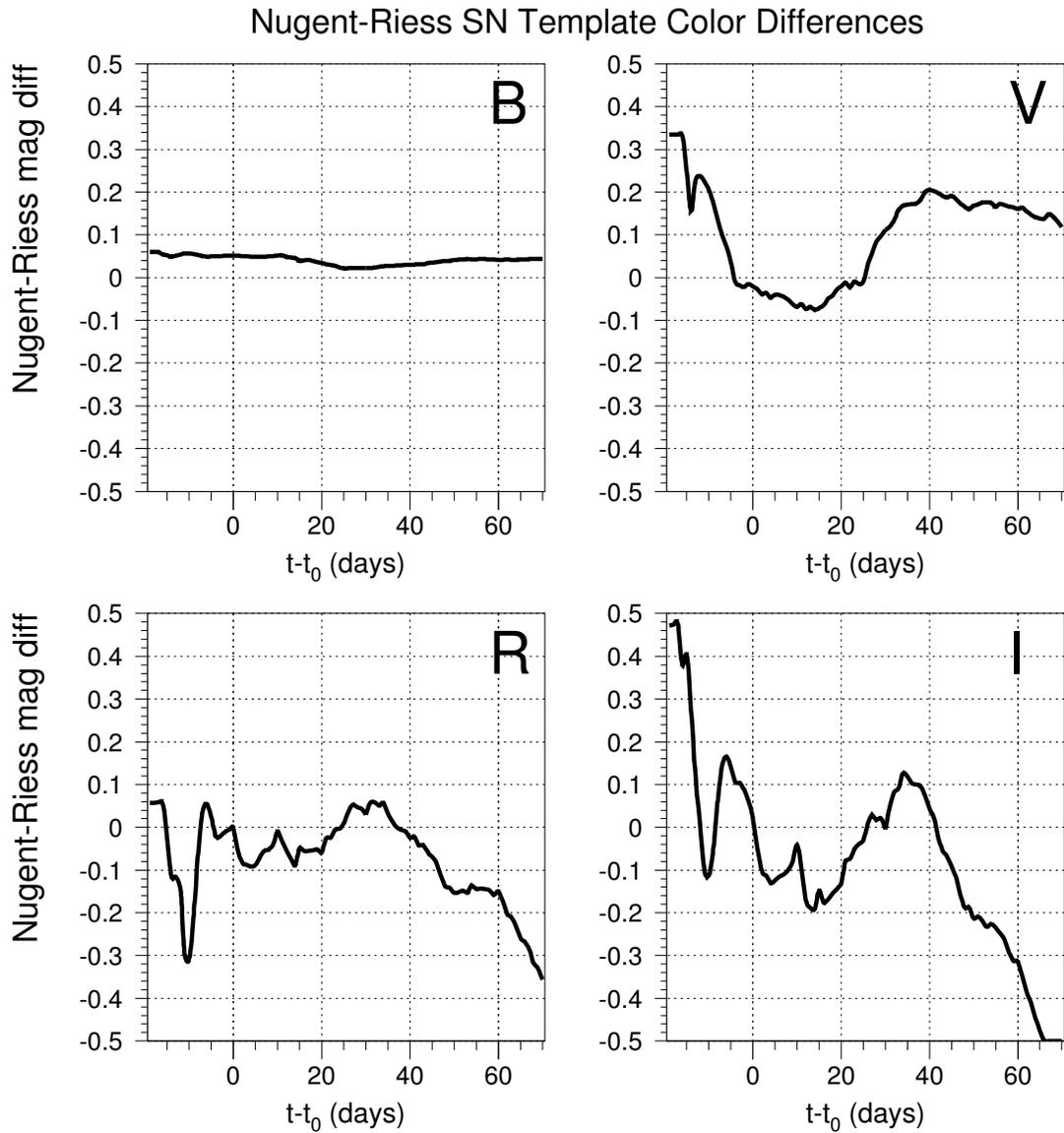


Figure 7: Synthetic color difference between Nugent and Riess SN Ia templates. m_B discrepancy is flat with epoch, while V,R,I discrepancies vary by few tenths of a magnitude.

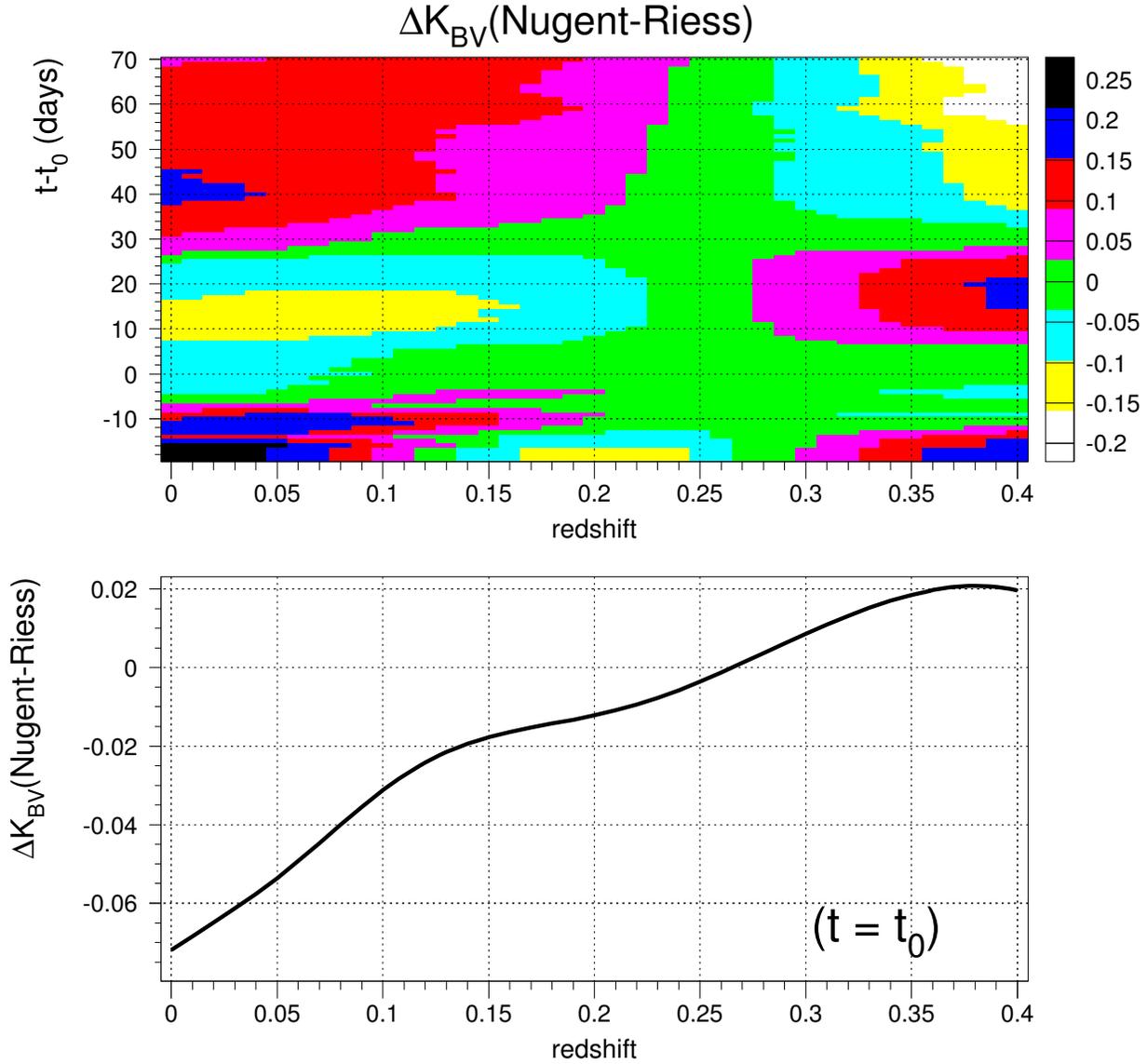


Figure 8: Top: difference in K_{BV} for Nugent and Riess SN Ia templates. Difference ΔK_V is shown in bins of redshift and epoch. Lower plot shows ΔK_V vs. redshift at the epoch corresponding to peak magnitude.

6 SDSS Filter Overlaps

Define filter overlap

$$\mathcal{O}_{ro} \equiv \frac{\int [f_\lambda(\lambda) \tilde{S}_o(\lambda(1+z)) / S_r(\lambda)] d\lambda}{\int f_\lambda(\lambda) d\lambda}$$

where $\tilde{S}_o = \min(S_o, S_r)$.

Note $\mathcal{O}_{ro} = 1$ for perfectly matched filters in observer and rest frames.

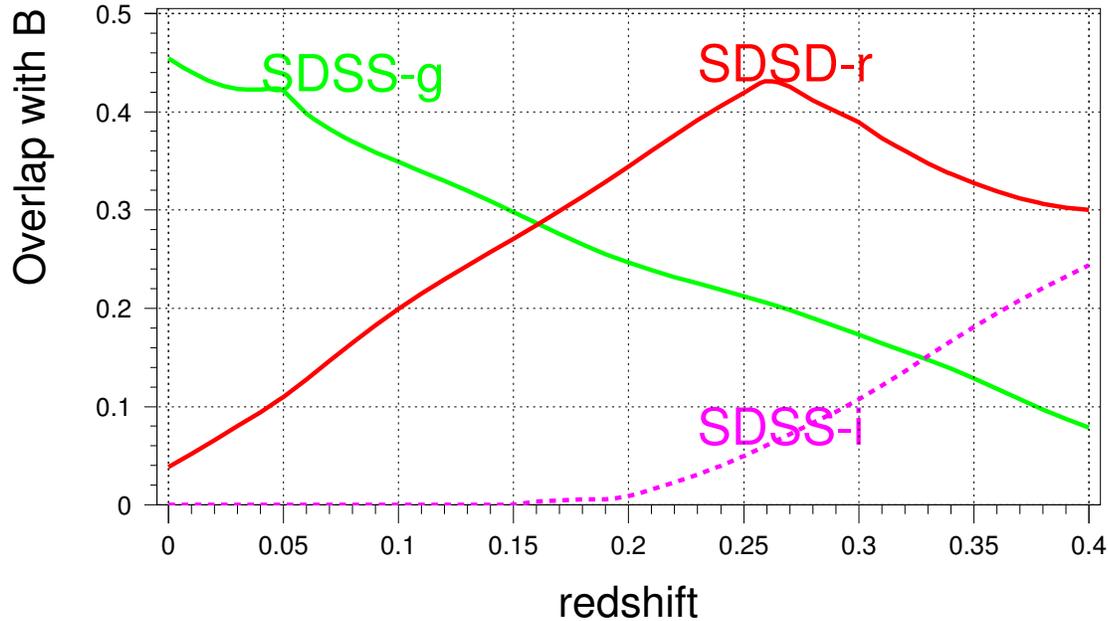


Figure 9: Filter overlaps \mathcal{O}_{Bg} , \mathcal{O}_{Br} , and \mathcal{O}_{Bi} vs. redshift. “B” refers to Johnson-B filter.

7 Remaining Confusion

- Which magnitude system ???
For example, Knopp 2003 (Sec 2.3 of Ap.J **598**, 102, 2003) suggests the Bessell system, while Nugent 2002 (Appendix A.3) states that Johnson-Cousins photon-based system “should and has been used in SCP analysis.”
- RK-Nugent comparisons agree at few percent level ... discrepancies not understood.
- large differences between Nugent and Riess SN Ia templates ??
- We only have fudged templates ... individual spectra to make templates are not (yet ??) available.
Need current spectra in order to:
 - add spectra from HET, ARC, etc .. to improve templates.
 - error analysis based on scatter of K-corrections.
 - re-evaluate which spectra to use.
 - test different fudging algorithms.
 - lightcurve fitting.