

# PHYX412-1 Fall 2008 : Quantum Mechanics I

## Homework Assignment 5 : Rotations

### 1. Rotations in Four Dimensions

A strange alien being lives in a Universe with *four* spatial directions, which she writes in the analog of Cartesian coordinates as  $\vec{x} = (x, y, z, w)$ . She wants to understand the implications of her world for the quantum mechanics of angular momentum.

(Note: don't be confused with special relativity, these are four Euclidean dimensions; when our alien studies the version of relativity relevant for her Universe, she studies Lorentz *five* vectors).

**A.** Just as we did in the case of three dimensions, we begin by studying classical rotations of four dimensional space. Rotations leave the norm of a vector in 4-space invariant. Prove that this implies that we can represent a four-space rotation as a  $4 \times 4$  orthogonal matrix acting on  $\vec{x}$ . Thus, her Universe's rotation group is  $O(4)$ .

**B.** A given rotation in 4-space mixes up coordinates of two of the axes, but leaves the coordinates of the other two axes invariant. So unlike our 3-space, we can't label a rotation by a single axis whose coordinate is invariant, we need a different labeling scheme which we will choose as the two axes which are transformed by the rotation. So for example the rotation  $R^{(x,y)}(\theta)$  rotates the  $x$  and  $y$  coordinates into each other by an amount  $\theta$ . Explain why this implies that there are *six* components of angular momentum in 4-space. Is angular momentum in a general dimensional space a vector?

**C.** Write down the six matrices which describe infinitesimal rotations between the cardinal axes to order  $\epsilon^2$  where  $\epsilon$  is the very small rotation parameter.

**D.** Work out the commutators of all of the rotations of part **C** to order  $\epsilon^2$ , and express the results in terms of the unit matrix and rotations by  $\epsilon^2$ .

**E.** Now we apply our results to a quantum theory. We write an infinitesimal quantum mechanical rotation to order  $\epsilon^2$  as,

$$\hat{D}\left(R^{(i,j)}(\epsilon)\right) \equiv \hat{1} - \frac{i}{\hbar} \hat{J}_{(i,j)} \epsilon - \frac{1}{\hbar^2} \hat{J}_{(i,j)}^2 \epsilon^2 + \dots$$

where the  $\hat{J}_{(i,j)}$  are the generators we are looking for and we can restrict  $i > j$  without a loss of generality. Our  $\hat{D}$ 's must satisfy the same multiplication rules as the classical rotations did. Use that fact to work out the commutators of the  $\hat{J}_{(i,j)}$  with each other.

**F.** In the four dimensional Universe, how many components of angular momentum can be measured simultaneously?

**G.** If we define a "total" angular momentum squared operator as,

$$\hat{J}^2 \equiv \sum_{i=1}^4 \sum_{j>i} \hat{J}_{(i,j)}^2$$

Can we measure it simultaneously with any of the components  $\hat{J}_{(i,j)}$ ?